

DESCRIPTION

METHOD OF CALCULATING A WIRE PACKING, APPARATUS THEREFOR, AND
PROGRAM THEREOF

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Technical Field

The present invention relates to a method of and an apparatus for calculation for obtaining an outside diameter of a wire packing by bundling and packing a plurality of wires into
10 the smallest possible circular shape by using a computer.

Background Art

A wire-like structure called a wire harness, which is formed by bundling a plurality of wires such as electrical wires
15 for electrically connecting electronic equipment, electronic components, and the like, is routed in a vehicle or a building structure. In recent years, from the viewpoint of improvement of space efficiency and the like, such a wire harness has come to be required to be as compact as possible without causing a
20 decline in electric characteristics. In consequence, there is a need to calculate the outside diameter of the wire harness more accurately. Conventionally, however, that calculation is conventionally performed by experience or a method of calculation shown below, and particularly effective
25 calculation method has not been proposed.

Referring to Figs. 8A and 8B, a problem in the conventional method of calculating the outside diameter of a wire harness will be described. Fig. 8A shows a wire harness which is made up of a relatively small number of wires, and Fig. 8B shows a
5 wire harness which is made up of a relatively large number of wires.

In the conventional method of calculation, as shown in Fig. 8A, when n wires a_1 are given, the cross section of these
10 wires a_1 , or a wire harness 10 consisting of these wires a_1 , is assumed to be circular. A diameter L of the wire harness 10 consisting of these wires a_1 is determined on the basis of the formula:

$$15 \quad \pi L^2/4 = K \sum (\pi l_1^2/4)$$

Here, l_1 denotes the diameter of the wire a_1 , and K denotes a gap coefficient. Since it is difficult to determine respective gap coefficients in such a manner as to fit the number
20 and layout of various wires, a fixed value is always used for all the cases irrespective of the number and layout of wires making up the wire harness 10.

However, as shown in Figs. 8A and 8B, even in the case
25 of the wire harnesses having equal diameters L , it is evident

that areas of their gaps l_1 and l_1' differ depending on the number and layout of the wires a_1 and a_1' making up the respective wire harnesses. If that diameter L is nevertheless determined by always using the gap coefficient K of a fixed value in the
5 above-described manner, that value becomes inaccurate, so that this method has been impractical.

Thus, there has been no practical method for determining the outside diameter of a wire harness which is made up of an
10 arbitrary number of wires. It goes without saying that there has been no effective method of calculation for obtaining the outside diameter of the wire harness when the wires are bundled and packed into the smallest circular form possible.

15 Disclosure of the Invention

Accordingly, in view of the above-described circumstances, an object of the invention is to provide an effective method of calculation for obtaining an outside diameter of a wire packing by bundling and packing an arbitrary
20 number of wires into the smallest possible circular shape, an apparatus and a program therefor.

To attain the above object, in accordance with a first aspect of the invention there is provided a method of
25 calculating a wire packing for obtaining an outside diameter

thereof by bundling and packing a plurality of wires into the smallest possible circular shape so as not to overlap each other by using a computer, characterized by comprising: an including-circle assuming step of assuming an including circle
5 which includes a plurality of circles arranged in a plane so as not to overlap each other by assuming that cross-sectional shapes of the plurality of wires are the plurality of circles having diameters corresponding to respective outer shapes thereof; a target-circle defining step of determining a target
10 circle which has the same center as that of the including circle and is slightly smaller than the including circle, and from which at least one of the plurality of circles protrudes; a searching step in which the circle protruding from the target circle is set as an insertion trial circle, and positions are
15 searched to which the plurality of circles other than the insertion trial circle can be moved as distantly as possible within the target circle without overlapping each other; an inserting step of inserting the insertion trial circle in a space in the target circle created by changing the layout of
20 the plurality of circles on the basis of a result of search in the searching step; and a first search controlling step in which in a case where all the insertion trial circles have been inserted in the target circle, a new target circle which is slightly smaller than a present one and has the insertion trial
25 circle is set, and the operation returns to the searching step,

wherein the including circle is made gradually small by repeatedly executing the target-circle defining step, the searching step, the inserting step, and the first search controlling step.

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In accordance with the above-described first aspect of the invention, the including circle surrounding the plurality of wires is made gradually small by repeatedly executing the target-circle defining step, the searching step, the inserting
10 step, and the first search controlling step by using a computer. Consequently, the outside diameter of the circle surrounding the plurality of wires is obtained efficiently.

The method of calculating a wire packing in accordance
15 with a second aspect of the invention devised to attain the above object is characterized in that, in the method of calculating a wire packing according to the first aspect, in the searching step, a circle Voronoi diagram is constructed by a circle set excluding the insertion trial circle and one of the plurality
20 of circle, and the target circle, and an examination is made with respect to the plurality of circles other than the insertion trial circle as to whether or not a center of the one circle tangent to both side circles forming each of boundary edges in the circle Voronoi diagram is located on the boundary
25 edge, to thereby search positions to which the circles can be

moved within the target circle.

In accordance with the above-described second aspect of the invention, the search of movement candidate positions of the insertion trial circle is extremely simplified by making use of a circle Voronoi diagram.

In the method of calculating a wire packing in accordance with a third aspect of the invention devised to attain the above object, the method of calculating a wire packing according to the first or second aspect is characterized by further comprising: a second search controlling step which is repeatedly executed together with the target-circle defining step, the searching step, the inserting step, and the first search controlling step, and in which in a case where the insertion of the insertion trial circle is impossible, the operation returns to the searching step after determining a new target circle which is of an intermediate size between the including circle and the present target circle and which has the insertion trial circle.

In accordance with the above-described third aspect of the invention, a second search controlling step is further comprised in which in a case where the insertion of the insertion trial circle is impossible, the operation returns to the

searching step after determining a new target circle which is of an intermediate size between the including circle and the present target circle. Consequently, the outside diameter of the circle surrounding the plurality of wires is obtained more efficiently.

To attain the above object, in accordance with a fourth aspect of the invention there is provided an apparatus for calculating a wire packing for obtaining an outside diameter thereof by bundling and packing a plurality of wires into the smallest possible circular shape so as not to overlap each other, characterized by comprising: including-circle assuming means for assuming an including circle which includes a plurality of circles arranged in a plane so as not to overlap each other by assuming that cross-sectional shapes of the plurality of wires are the plurality of circles having diameters corresponding to respective outer shapes thereof; target-circle defining means for determining a target circle which has the same center as that of the including circle and is slightly smaller than the including circle, and from which at least one of the plurality of circles protrudes; searching means in which the circle protruding from the target circle is set as an insertion trial circle, and positions are searched to which the plurality of circles other than the insertion trial circle can be moved as distantly as possible within the target circle without

overlapping each other; inserting means for inserting the insertion trial circle in a space in the target circle created by changing the layout of the plurality of circles on the basis of a result of search by the searching means; first search
5 controlling means in which in a case where all the insertion trial circles have been inserted in the target circle, a new target circle which is slightly smaller than a present one and has the insertion trial circle is set, and the search by the searching means is then effected; input means for inputting
10 initial information on the plurality of wires; and output means for outputting at least the outside diameter of the including circle.

In accordance with the above-described fourth aspect of
15 the invention, initial information on the plurality of wires is inputted by the input means, the including circle surrounding the plurality of wires is made gradually small by the target-circle defining means, the searching means, the inserting means, and the first search controlling means, and
20 the outside diameter of that including circle is outputted by the output means. Consequently, the outside diameter of the circle surrounding the plurality of wires is obtained efficiently.

25 The apparatus for calculating a wire packing in

accordance with a fifth aspect of the invention devised to attain the above object is characterized in that, in the apparatus for calculating a wire packing according to the fourth aspect, the output means outputs position information on the including circle and the plurality of circles.

According to the above-described fifth aspect of the invention, since the position information on the including circle and the plurality of circles is outputted, the outside diameter of the circle surrounding them, including the layout of the plurality of wires, is obtained efficiently.

The apparatus for calculating a wire packing in accordance with a sixth aspect of the invention devised to attain the above object is characterized in that, in the apparatus for calculating a wire packing according to the fourth or fifth aspect, the searching means includes second searching means in which a circle Voronoi diagram is constructed by a circle set excluding the insertion trial circle and one of the plurality of circle, and the target circle, and in which an examination is made with respect to the plurality of circles other than the insertion trial circle as to whether or not a center of the one circle tangent to both side circles forming each of boundary edges in the circle Voronoi diagram is located on the boundary edge, to thereby search positions to which the

circles can be moved within the target circle.

In accordance with the above-described sixth aspect of the invention, the search of movement candidate positions of the insertion trial circle is extremely simplified by making
5 use of a circle Voronoi diagram in the second searching means.

In the apparatus for calculating a wire packing in accordance with a seventh aspect of the invention devised to
10 attain the above object, the apparatus for calculating a wire packing according to any one of fourth, fifth, and sixth aspects is characterized by further comprising: second search controlling means which, in a case where the insertion of the insertion trial circle is impossible, causes the search by the
15 searching means to be effected after determining a new target circle which is of an intermediate size between the including circle and the present target circle and which has the insertion trial circle.

20 In accordance with the above-described seventh aspect of the invention, in a case where the insertion of the insertion trial circle by the second search controlling means is impossible, the search by the searching means is effected again after determining a target circle which is of an intermediate
25 size between the including circle and the present target circle.

Therefore, the outside diameter of the circle surrounding the plurality of wires is obtained more efficiently.

Brief Description of the Drawings

5 Fig. 1 is a block diagram illustrating an example of a hardware configuration for realizing a calculation method and an apparatus therefor in accordance with the invention;

 Fig. 2 is a flowchart illustrating a basic processing procedure in accordance with an embodiment of the calculation
10 method of the invention;

 Fig. 3A is a diagram illustrating an initial state;

 Fig. 3B is a diagram illustrating an insertion trial circle protruding from a target circle;

 Fig. 3C is a diagram illustrating a state in which the
15 insertion trial circle shown in Fig. 3B is inserted in the target circle;

 Fig. 3D is a diagram illustrating a final result;

 Fig. 4 is a flowchart illustrating search and insertion processing shown in Fig. 2;

20 Fig. 5 is a flowchart illustrating first search processing;

 Fig. 6 is a flowchart illustrating second search processing;

 Fig. 7A is a diagram illustrating an example of a circle
25 set ;

Figs. 7B and 7C are a circle Voronoi diagram and a Laguerre circle Voronoi diagram, respectively, with respect to the circle set shown in Fig. 7A;

Fig. 8A is a diagram illustrating a wire harness which
5 is made up of a relatively small number of wires; and

Fig. 8B is a diagram illustrating a wire harness which is made up of a relatively large number of wires.

Best Mode for Carrying out the Invention

10 Referring now to the accompanying drawings, a description will be given of an embodiment of the invention.

First, referring to Fig. 1, a description will be given of a hardware configuration for realizing a method of calculating a wire packing. Fig. 1 is a block diagram
15 illustrating an example of a hardware configuration for realizing a calculation method and an apparatus therefor in accordance with the invention.

As shown in Fig. 1, the hardware configuration is realized
20 by a known personal computer, a general-purpose computer, or the like. This computer is comprised of an input unit 1, an input/output interface circuit (I/O) 2, a central processing unit (CPU) 3, a memory 4, an output unit 5 and a read/write unit 6. The input unit 1, the memory 4, the output unit 5 and the
25 read/write unit 6 are electrically connected to the CPU 3

through the I/O 2 and the like.

The input unit 1 is, for example, a keyboard and a mouse device which are used for inputting input data in processing which will be described later. The CPU 3 includes a control section 31 for controlling the input unit 1, the output unit 5, and the like, as well as an operation part 32 for effecting processing concerning the calculation method, which will be described later, in accordance with programs stored in the memory 4.

The memory 4 includes a program memory 41 for storing programs and the like corresponding to each processing in accordance with the calculation method which will be described later, as well as an operation memory 42 to which work areas for various processing to be performed by the CPU 3 are allotted. The output unit 5 is, for example, a monitor display and a printer for outputting the results of processing performed by the CPU.

The read/write unit 6 is a device which reads out a wire packing calculating program 7a according to the present invention which stored in a recording medium 7 such as CD-ROM (for example, a program for processing procedures shown in Figs. 2, 4, 5 and 6 described later), and transmits it to the program memory 41. The read/write unit 6 has a function of writing the

calculation result in the recording medium 7. Incidentally, the computer may includes a communication interface such as not-shown modem board and LAN card.

The CPU 3 installs the wire packing calculating program 7a read out by the read/write unit 6 in a program memory 41 of the memory 4. After power the computer on, the program 7a is executed and the computer functions as the apparatus for calculating the wire packing. The wire packing calculating program 7a is capable of being installed in, for example, a personal computer and general-purpose computers having the above construction, and when the program is installed, the computer functions as the apparatus for calculating the wire packing.

The wire packing calculating program 7a may be provided not only through the recording medium such as CD-ROM but also through a communication lint such as Internet, dedicated line and LAN, for example.

Next, referring to Figs. 2 to 7, a description will be given of a processing procedure concerning an embodiment of the calculation method in accordance with the invention. Accordingly, referring to Fig. 2, a description will be first given of a basic processing procedure of this calculation method. Fig. 2 is a flowchart illustrating a basic processing procedure in accordance with an embodiment of the calculation method of the invention.

In this calculation method, the problem resolves itself into one in which cross-sectional shapes of a plurality of wires making up the wire harness are assumed to be a plurality of circles having diameters corresponding to the respective outer shapes thereof, and when n circular cylinders having these circles in their cross sections are bundled, the size of a circle capable of surrounding and accommodating the overall circles is examined. In practice, an effective calculation method is conceived for bundling and packing a plurality of wires into the smallest possible circular shape and for obtaining its outside diameter.

In the basic processing shown in Fig. 2, radii r_1, r_2, \dots, r_n of n circles c_1, c_2, \dots, c_n whose outer shapes respectively correspond to cross-sectional shapes of a plurality of wires such as electric wires making up the wire harness, a number p which is smaller than and sufficiently close to 1, e.g., $p = 0.95$, a terminating reference value ε which is a sufficiently small integer, e.g., the terminating reference value $\varepsilon = \min((r_1, r_2, \dots, r_n)/100)$ are given as input information.

In addition, a radius R of the smallest possible circle for packing the n circles c_1, c_2, \dots, c_n so as not to overlap each other, as well as position information on a circle C and

the circles c_1, c_2, \dots, c_n at this time are given as the output information.

For this reason, in Step S1 shown in Fig. 2, the circles
5 c_1, c_2, \dots, c_n are laid out in a plane so as not to overlap each other, and a large circle surrounding them, i.e., an including circle C, is found.

Next, in Steps S2, S3, and S4, a circle which has the same
10 center as that of the aforementioned including circle C and whose radius is p-fold that of the including circle C, i.e., a target circle D, is determined. Namely, in a loop consisting of Steps S2, S3, and S4, a target circle D is determined which has the same center as that of the including circle C and is
15 slightly smaller than the including circle C, and from which at least one of the plurality of circles c_1, c_2, \dots, c_n protrudes. It should be noted that, in the following processing steps, the layout is changed so that the circles c_1, c_2, \dots, c_n are accommodated in the target circle D.

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Next, in Step S5, search and insertion processing is effected. Namely, here, circles other than an arbitrary circle c_1 protruding from the target circle D are removed in order starting with one whose distance from the circle c_1 is largest.
25 Those circles which can be placed at farther positions are moved

as distantly as possible, and when such movement is impossible, the circles are left at the present positions. Then, an attempt is made to move the single circle c_1 to a space created by such movement, i.e., an insertion is attempted. It should be noted
5 that the processing of this Step S3 will be described later with reference to Figs. 4 to 7.

Next, in Step S6, a determination is made as to whether or not the insertion of the circle c_1 has been successful in
10 Step S5 above. If successful (Y in Step S6), the operation returns to Step S3, and if not (N in Step S6), the operation proceeds to Step S7. When the operation returns to Step S3, a determination is made as to whether or not there is any other protruding circle. If there is, the search and insertion
15 processing in Step S5 is effected again with respect to this protruding circle. If there is not, the operation proceeds to Step S4 to effect the same processing as described above.

Meanwhile, in Step S7, a circle of an intermediate size
20 between the aforementioned including circle C and the aforementioned target circle D for which the insertion was unsuccessful is newly set as the target circle D. Next, in Step S8, a determination is made as to whether the difference between the radii of the including circle and the target circle D used
25 in the processing in Step S7 above is equal to or less than the

aforementioned terminating reference value ϵ . If this difference is greater than the terminating reference value ϵ (N in Step S8), the operation returns to Step S3 to repeat the same processing as described above, whereas if this difference
5 is equal to or less than the terminating reference value ϵ (Y in Step S8), the operation proceeds to Step S9.

In Step S9, the radius of this including circle C is outputted to the output unit 5 as the final radius R of the wire
10 harness. In addition, the position information on the circle C and the circles C_1, C_2, \dots, C_n at this time are also outputted to the output unit 5. These outputs may be given on a monitor display or may be printed out on paper. It should be noted that the aforementioned number p and terminating reference value ϵ
15 may be slightly changed, as required.

The behavior of the respective circles according to the above-described processing procedure will be shown with reference to Figs. 3A to 3D. Figs. 3A to 3D are diagrams
20 illustrating the behavior according to the processing procedure shown in Fig. 2. In particular, Fig. 3A shows an initial state; Fig. 3B shows an insertion trial circle protruding from the target circle; Fig. 3C shows a state in which the insertion trial circle shown in Fig. 3B is inserted in the target circle; and
25 Fig. 3D is a diagram illustrating a final result.

Fig. 3A shows the initial layout of the n circles c_i given as well as the including circle C surrounding them. Fig. 3B shows a state in which processing is underway, and illustrates the target circle D which is slightly smaller than the presently obtained including circle C as well as the insertion trial circle c_n which is one of the circles protruding from this target circle D and whose insertion is tried.

In addition, Fig. 3C shows a state after the search and insertion processing in Step S5 shown in Fig. 2 was carried out with respect to the insertion trial circle c_n shown in Fig. 3B. It should be noted that, in Fig. 3C, circles m_1 (a circle set surrounding the coarse hatchings) show a moved circle set which was moved to insert the insertion trial circle c_n in the above-described search and insertion processing. It should be noted that, as can be understood from this drawing, there are cases where the other protruding circles are also packed in the target circle D in the process of the insertion processing of the insertion trial circle c_n . Then, the result in which insertion processing was effected with respect to all the protruding circles is shown in Fig. 3D.

Thus, the layout of the plurality of wires making up the wire harness is changed such that they are located as distantly

as possible from the wire protruding from the including circle,
and the protruding wire is inserted in the space thus created.
As this operation is repeatedly calculated, the outside
diameter of the wire harness surrounding the plurality of wires
5 is efficiently obtained.

Next, referring to Fig. 4, a description will be given
of the search and insertion processing in Step S5 shown in Fig.
2 referred to above. Fig. 4 is a flowchart illustrating the
10 search and insertion processing in Fig. 2.

In the search and insertion processing shown in Fig. 4,
radii r_i of n circles c_i , their centers (x_i, y_i) , $i = 1, 2, \dots,$
 n , and the target circle D are given as input information. It
15 is assumed, however, that the n circles c_i do not overlap each
other, and that the final circle c_n protrudes from the target
circle D . There may be other protruding circles.

Meanwhile, by way of output information, if the final
20 circle c_n can be inserted in the target circle D without causing
the circles already placed in the target circle D to protrude
from this target circle D , the central positions of the n circles
for realizing that insertion are outputted as a successful
result. If that insertion is impossible, a message to that
25 effect is outputted as an unsuccessful result.

First, in Step S51 in the search and insertion processing, the n circles c_1 are rearranged in the order of distance from the aforementioned final circle c_n . Specifically, this order is based on the distance between the center of each of the n circles c_1 and the center of the final circle c_n . Here, the circle numbers as the result of the rearrangement are newly set as c_1, c_2, \dots, c_n for the sake of simplicity. It should be noted that this final circle will be hereafter referred to as an insertion trial circle.

Next, processing shown in Steps S52 to S54a (or Step S54b) is effected with respect to $i = 1, 2, \dots, n - 1$. In Step S52, search processing is carried out. Namely, a search is made of a movement candidate position to which the circle c_i can be moved without overlapping the other circles within the target circle D . Specifically, in this search processing, first search processing shown in Fig. 5 or second search processing shown in Fig. 6 is carried out. In the first search processing, a search is made of such a movement candidate position that the circle c_i becomes farther from the insertion trial circle c_n than the present position of the circle c_i without overlapping the other circles within the target circle D . In addition, in the second search processing shown in Fig. 6, by using the concept of a circle Voronoi diagram, a search is made of a

movement candidate position to which the circle c_1 can be moved without overlapping the other circles within the target circle D. These searches will be described later.

5 Then, in Steps S53, S54a, and S54b, if a movement candidate position is present in the above-described search processing (Y in Step S53), the circle c_1 is moved to a position which is farthest from the insertion trial circle c_n among such movement candidate positions (Step S54a). If there is no movement
10 candidate position (N in Step S53), the circle c_1 is left at the present position (Step S54b). After such processing is effected with respect to $i = 1, 2, \dots, n$, the operation proceeds to Step S55. It should be noted that the aforementioned Steps S52 to S54 correspond to the search process in the claims.

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Next, in Step S55, the insertion of the insertion trial circle c_n is tried with respect to the space in the target circle D created by the loop processing consisting of the aforementioned Steps S52 to S54a (or Step 54b).

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Then in Steps S56, S57a, and S57b, if the insertion is successful by the trial of the insertion (Y in Step S56), the insertion trial circle c_n is moved to that position (Step S57a). If the insertion is not successful (N in Step S56), a message
25 to that effect is outputted (Step S57b). It should be noted

that at the time of the success the central positions of the
n circles for realizing it are outputted. Then, when the series
of processing consisting of Steps S51 to S56a (or Step S56b)
is completed, the operation returns to the ensuing processing
5 shown in Fig. 2.

Referring to Figs. 5 and 6, a description will be given
of two examples of the above-described search processing.
First, the first search processing will be described with
10 reference to Fig. 5. Fig. 5 is a flowchart illustrating the
first search processing.

In the first search processing shown in Fig. 5, attention
is paid to the fact that that when there is a space for moving
15 the n circles c_1 , in a state in which the circle c_1 is moved
to a most distant position from the aforementioned insertion
trial circle c_n , the circle c_1 should be tangent to two circles.
However, there are cases where one of these two tangent circles
is the aforementioned target circle D. Accordingly, here, a
20 set formed by the whole of the given n circles c_1 and the target
circle D is set as $S = \{n \text{ circles } c_1, c_2, \dots, c_n, D\}$. Then,
processing shown in the following Steps S521 to S529 is effected
with respect to all the two circles c_j and c_k other than the
circle $c_1 \in S$.

First, in Step S521, two positions are searched where the circle c_i with a radius r_i is tangent to both the circle c_j and the circle c_k . However, it is assumed that if the circle c_j or the circle c_k is a circle other than the target circle D , the circle c_i is tangent to that circle from the outside, and if the circle c_j or the circle c_k is the target circle D , the circle c_i is tangent to that circle from the inside. There are only two such positions, and the centers in such a case are set as (x'_i, y'_i) and (x''_i, y''_i) , respectively.

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Next, in Step S522, a determination is made as to whether or not if the circle c_i is moved to one of the aforementioned two positions, the circle c_i becomes more distant from the insertion trial circle c_n than the present position. Namely, a comparison is made between a distance X' from one center (x'_i, y'_i) to the center of the insertion trial circle c_n and a distance X from the center of the circle c_i at the present position to the center of the insertion trial circle c_n . If the distance X' is greater than the distance X (Y in Step S522), the operation proceeds to Step S523; if not (N in Step S522), the operation proceeds to Step S526 which will be described later.

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In Step S523, an examination is made as to whether or not the circle c_i with the radius r_i , when placed at the aforementioned center (x'_i, y'_i) , overlaps any of all the

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circles other than the circle c_1 , the circle c_j , the circle c_k , and the target circle D. The overlap is determined in Step S524. Here, if it is determined that the circle c_1 does not overlap any circle (N in Step S524), the operation proceeds to Step S525.

5 In Step S525, the aforementioned center (x'_1, y'_1) is added as one of the movement candidate positions of the circle c_1 ; otherwise (Y in Step S524), the operation proceeds to Step S526.

Further, the aforementioned center (x'_1, y'_1) is replaced
10 by the other center (x''_1, y''_1) , and the following processing in Steps S526 to S529 is effected in the same way as Steps S522 to S525 above. In Step S526, a determination is made as to whether or not if the circle c_1 is moved to the other one of the aforementioned two positions, the circle c_1 becomes more
15 distant from the insertion trial circle c_n than the present position. Namely, a comparison is made between a distance X'' from the other center (x''_1, y''_1) to the center of the insertion trial circle c_n and the distance X from the center of the circle c_1 at the present position to the center of the insertion trial
20 circle c_n . If the distance X'' is greater than the distance X (Y in Step S526), the operation proceeds to Step S527; if not (N in Step S526), the operation proceeds directly to a next one in the loop.

25 In Step S527, an examination is made as to whether or not

the circle c_1 with the radius r_1 , when placed at the aforementioned center (x''_1, y''_1) , overlaps any of all the circles other than the circle c_1 , the circle c_j , the circle c_k , and the target circle D. The overlap is determined in Step S528.

5 Here, if it is determined that the circle c_1 does not overlap any circle (N in Step S528), the operation proceeds to Step S529. In Step S529, the aforementioned center (x''_1, y''_1) is added as one of the movement candidate positions of the circle c_1 ; otherwise (Y in Step S528), the operation directly proceeds to
10 a next one in the loop. When such processing is effected with respect to all the two circles c_j and c_k other than the circle c_1 , the operation returns to the immediately following processing shown in Fig. 4.

15 By using the above-described first search processing, the calculation of the outside diameter of the wire harness, which is conventionally performed by the method shown in Fig. 8 or by experience, can be improved and performed more accurately. Accordingly, an aid is provided in the design of the wire harness.
20 On the other hand, there arises a problem in that if the first search processing is used, the amount of calculation becomes enormously large. Namely, in the first search processing shown in Fig. 5 referred to above, since the above-described operation is effected with respect to the set of the circle c_1 , the circle
25 c_j , and the circle c_k , the calculation time becomes $O(n^3)$. In

the search and insertion processing shown in Fig. 4, since the processing is effected with respect to all of $I = 1, 2, \dots, n$, the calculation time becomes $O(n^4)$. Further, in the processing shown in Fig. 2, since processing is effected repeatedly by incorporating the processing shown in Fig. 4, the total amount of calculation becomes enormously large. Improvement is made in this respect in the second search processing shown in Fig. 6 below.

Fig. 6 is a flowchart illustrating the second search processing. Fig. 7A is a diagram illustrating an example of a circle set. Figs. 7B and 7C are a circle Voronoi diagram and a Laguerre circle Voronoi diagram, respectively, with respect to the circle set shown in Fig. 7A.

First, a basic concept of this second search processing will be shown. In this second search processing, the search of a movement candidate position of an insertion trial circle c_1 is made efficient by using the concept of a known Voronoi diagram. Namely, in the above-described first search processing, positions where the circle c_1 is tangent to all sets of circles c_j and c_k are determined. However, if the concept of the Voronoi diagram is utilized, the candidates can be limited.

When a finite number of circles not overlapping each other in a plane are given, the plane can be divided by determining to which circle a given circle is closest. This divided diagram is called a circle Voronoi diagram. This circle Voronoi diagram is also shown in document 1 (A. Okabe, B. Boots, K. Sugihara and S.N. Choi: Spatial Tessellations -- Concepts and Applications of Voronoi Diagrams, 2nd Edition. John Wiley and Sons, Chichester, 2000).

For example, a circle Voronoi diagram with respect to a circle set shown in Fig. 7A is shown in Fig. 7B. A point on a boundary edge e_j which is called a Voronoi edge in Fig. 7B has a characteristic that the point is equidistant from two circles c_k and c_l and the other circles are located more distantly.

Accordingly, a circle which is tangent to the two circles c_k and c_l and does not overlap other circles has a center on the boundary edge e_j of the circle Voronoi diagram. Accordingly, as for the movement candidate positions of the circle c_l , it suffices to search only the sets of two circles c_k and c_l

sandwiching the boundary edge e_j of the circle Voronoi diagram. Since the number of the boundary edges e_j of the circle Voronoi diagram of n circles is proportional to n , the calculation time of the sets of the circles c_k and c_l to be searched is $O(n^2)$ in the first search processing shown in Fig. 5 referred to above,

whereas the calculation time of the sets of the circles c_k and

c_1 to be searched is $O(n)$ in this case.

Further, in the first search processing shown in Fig. 5 referred to above, a search is made of the overlap with all the circles c_j and c_k other than the circle c_1 with respect to the movement candidate positions of the circle c_1 tangent to the two circles c_k and c_1 . Here, however, that search is made unnecessary. Namely, it is sufficient if a search is made as to whether or not the movement candidate positions of the circles c_1 are located on the boundary edges e_j . This is because it can be derived from the characteristic of the Voronoi diagram that if the circle c_1 is located on the boundary edge e_j , the circle c_1 does not overlap another circle, and if the circle c_1 is not located on the boundary edge e_j , the circle c_1 overlaps another circle. Accordingly, the calculation time of $O(n)$ can be reduced to $O(1)$.

The processing procedure of the second search processing based on such a concept is shown in Fig. 6 referred to below. In Step S521' in Fig. 6, a circle Voronoi diagram is constructed with respect to the aforementioned circle set $S - \{c_1\}$, i.e., all the circles other than the circle c_1 . Here, since the circle set $S - \{c_1\}$ consists of n circles, the number of boundary edges is also proportional to n .

Then, processing in the following Steps S522' to S525' is performed with respect to each boundary edge e_j ($j = 1, 2, \dots, n$).

5 In Step S522', a circle c'_i with a radius r_i tangent to the circles c_k and c_1 on both sides of the boundary edge e_j is plotted. Here again, it is assumed that if the circle c_k or the circle c_1 is a circle other than the target circle D , the circle c'_i is tangent to that circle from the outside, and if
10 the circle c_k or the circle c_1 is the target circle D , the circle c'_i is tangent to that circle from the inside. Incidentally, there are only two such positions.

Next, if it is determined in Step S523' that the
15 above-described tangent circle c'_i with the radius r_i is present (Y in Step S523'), and if it is determined in Step S524' that its center is located on the boundary edge e_j (Y in Step S524'), the operation proceeds to Step S525' to add this circle c'_i as the movement candidate position of the circle c_1 . Otherwise
20 (N in Step S523' and N in Step S524'), the operation proceeds directly to the next step. If such processing is effected with respect to all the boundary edges e_j , the operation returns to the following processing shown in Fig. 4.

25 As is apparent from the foregoing description, it can be

appreciated that the search of movement candidate positions of the circles c_i can be extremely simplified by utilizing the concept of the Voronoi diagram. The aforementioned document 1 shows that a circle Voronoi diagram of n circles can be constructed in the calculation time of $O(n \log n)$. Accordingly, the processing of the aforementioned Step S521' can be executed in $O(n \log n)$. Meanwhile, since the number of the boundary edges of the circle Voronoi diagram of the n circles is only proportional to n , the processing of the aforementioned Steps S522' to S524' can be executed in $O(n)$ time. It follows from above that the calculation time of the second search processing shown in Fig. 6 becomes $O(n \log n)$. By way of reference, since the calculation time of $O(n^3)$ is required in the first search processing shown in Fig. 5, it can be seen that the efficiency improves substantially. Incidentally, if the second search processing in Fig. 6 is incorporated into the search and insertion processing in Fig. 4, since the processing in Fig. 6 is executed $O(n)$ times in the search and insertion processing in Fig. 4, the calculation time of the search and insertion processing in Fig. 4 becomes $O(n^2 \log n)$.

It should be noted that a simple method of calculating the above-described circle Voronoi diagram is a method in which a Laguerre Voronoi diagram described in the aforementioned document 1 is constructed, and is then converted into a circle

Voronoi diagram by the flip operation of a side described in document 2 (D.S. Kim and K. Sugihara: Voronoi diagram of a circle set from Voronoi diagram of a point set, I. Topology. Computer Aided Geometric Design, vol. 18 (2001), pp. 541 - 562) and document 3 (D.S. Kim and K. Sugihara: Voronoi diagram of a circle set from Voronoi diagram of a point set, II. Geometry. Computer Aided Geometric Design, vol. 18 (2001), pp. 563 - 585).

As described above, according to this embodiment, the outside diameter of the wire harness surrounding the plurality of wires can be efficiently obtained by repeatedly calculating the operation in which the layout of the plurality of wires making up the wire harness is changed such that, by using a computer, the wires are moved as distantly as possible from the wire protruding from the including circle, and the protruding wire is inserted in the space thus created. In particular, by adopting the concept of the circular Voronoi diagram, it becomes possible to obtain the outside diameter of the wire harness extremely simply and in a short time.

It should be noted that, in the above-described embodiment, the radius is outputted to determine the outside diameter of the wire harness, but it goes without saying that the diameter may be outputted instead. In addition, an arrangement may be provided such that not only is the radius

of the wire harness outputted in the above-described manner,
but information indicating the layout of the respective wires
is outputted. In addition, the values of p and \square are not limited
to the values shown in the above-described embodiment, and may
5 be modified, as required, within the scope of the gist of the
invention.

In accordance with the first aspect of the invention, the
including circle surrounding the plurality of wires is made
10 gradually small by repeatedly executing the target-circle
defining step, the searching step, the inserting step, and the
first search controlling step by using a computer.
Consequently, the outside diameter of the circle surrounding
the plurality of wires can be obtained efficiently.

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In accordance with the second aspect of the invention,
the search of movement candidate positions of the insertion
trial circle is extremely simplified by making use of a circle
Voronoi diagram. Accordingly, the outside diameter of the
20 circle surrounding the plurality of wires can be obtained in
a short time.

In accordance with the third aspect of the invention, a
second search controlling step is further comprised in which
25 in a case where the insertion of the insertion trial circle is

impossible, the operation returns to the searching step after determining a new target circle which is of an intermediate size between the including circle and the present target circle. Consequently, the outside diameter of the circle surrounding
5 the plurality of wires can be obtained more efficiently.

In accordance with the fourth aspect of the invention, initial information on the plurality of wires is inputted by the input means, the including circle surrounding the plurality
10 of wires is made gradually small by the target-circle defining means, the searching means, the inserting means, and the first search controlling means, and the outside diameter of that including circle is outputted by the output means. Consequently, the outside diameter of the circle surrounding
15 the plurality of wires can be obtained efficiently.

According to the fifth aspect of the invention, since the position information on the including circle and the plurality of circles is outputted, the outside diameter of the circle
20 surrounding them, including the layout of the plurality of wires, can be obtained efficiently.

In accordance with the sixth aspect of the invention, the search of movement candidate positions of the insertion trial
25 circle is extremely simplified by making use of a circle Voronoi

diagram by the second searching means. Accordingly, the outside diameter of the circle surrounding the plurality of wires can be obtained in a short time.

5 In accordance with the seventh aspect of the invention, in a case where the insertion of the insertion trial circle by the second search controlling means is impossible, the search by the searching means is effected again after determining a target circle which is of an intermediate size between the
10 including circle and the present target circle. Therefore, the outside diameter of the circle surrounding the plurality of wires can be obtained more efficiently.